

# A NOVEL APPROACH FOR DETAIL SURVEYS BY THE MOTORIZED GPSSIT CONCEPT IN RESIDENTIALS AREAS AND ITS APPLICATION

*Um novo enfoque para pesquisas em detalhes pelo conceito motorizado GPSSIT em áreas residenciais e sua aplicação*

IBRAHIM KALAYCI  
SERMET OGUTCU

Necmettin Erbakan Konya University  
Engineering Faculty  
Department of Surveying Engineering  
Konya 42090 Turkey  
ikalayci@konya.edu.tr; sermetogutcu@konya.edu.tr

## ABSTRACT

This paper introduces the usage and reliability of Motorized GPSSIT technique which is a novel approach for surveying. It reviews the advantages of Motorized GPSSIT concept and also considers to provide GNSS accuracy in the process of surveying especially for the cases which cannot be surveyed directly by the satellite navigation systems (GPS-GNSS), such as closely packed residential areas, tall buildings, trees, etc., and also places which GNSS receivers cannot be work efficiently due to signal interferences. In this technique, all the survey instruments are installed on a bed of a pick-up truck whereas in present techniques they are installed on the ground, therefore it is called Motorized GPSSIT. Study area was chosen within the housing area of our campus. In this area, classical surveying, GPSSIT and Motorized GPSSIT were performed to collect data for comparison and for the analysis of this technique's usability and reliability. Stop and Go and RTK surveying techniques were performed with GPSSIT and Motorized GPSSIT concepts. It is shown that the Motorized GPSSIT technique is applicable as other present techniques in terms of accuracy and reliability.

**Keywords:** GPS; GNSS; Detail Surveys; GPSSIT; Virtual Station; Motorized GPSSIT.

## RESUMO

Este trabalho introduz o uso e a confiabilidade da técnica motorizada GPSSIT, que é um novo enfoque para a pesquisa. Revê-se as vantagens de conceito motorizado e também considera a disponibilidade da precisão GNSS no processo de pesquisa especialmente para os casos que não foram estudados diretamente do sistema de navegação por satélite (GPS-GNSS) tais como em áreas residenciais bem fechadas, prédios altos, árvores, etc, e também em locais onde os receptores GNSS não podem ser operados eficientemente devido a interferência de sinal. Nesta técnica, todos os instrumentos da pesquisa são instalados numa plataforma de caminhão pick-up enquanto que nas presentes técnicas, eles são instalados no solo, e portanto são denominados como motorizados GPSSIT. O estudo foi realizado dentro de uma área construída no nosso campus. Nesta área, a pesquisa clássica, GPSSIT e motorizada GPSSIT foram realizadas para a coleta de dados para a comparação e análise da confiabilidade e usabilidade da técnica “stop and go” e técnicas de pesquisa RTK foram realizadas com os conceitos GPSSIT e motorizados GPSSIT. Foi possível demonstrar que a técnica é aplicável como outras técnicas atuais em termos de acurácia e confiabilidade.

**Palavras-chave:** GPS; GNSS; Levantamentos de Detalhes; GPSSIT; Estação Virtual; GPSSIT Motorizado.

## 1.INTRODUCTION

Before total station came into existence as a surveying instrument, surveyors generally used theodolites and steel band or Electronic Distance Measurement (EDM) device together for angle and distance measurement in order to propagate coordinates from one point to another using the technique of traversing. The Total Station simplified the procedure of traversing by integrating the EDM into the theodolite and reading all measurements digitally (CRANENBROECK J, 2005).

The introduction of satellite positioning systems has provided the surveyor with an additional measurement technology to perform survey tasks. Recently, there is an increase demand on positioning techniques based on Global Navigation Satellite System (GNSS) such as Global Positioning System. Cellular network infrastructure or on the integration of two technologies using for any kind of surveying such as land surveying, cadastral surveying or deformation surveying (ROBERTS C, 2005; HAMILTON J, 2012). Concept of satellite navigation system is the resection from satellites which is called three dimensional trilateration. For resection, GPS or GNSS receivers calculates distance to at least four satellites using travel time of radio signals therefore receiver's position can be determined. Using GNSS technique has lots of advantage compared to the other classical surveying techniques. In terms of speed, accuracy and reliability, GNSS system generally using commonly in the application field which GNSS system can perform directly and work efficiently with satisfying accuracy.

Despite many advantages, surveying using only total stations or satellite positioning systems have own unique disadvantages. Surveying with a total station, unlike GPS surveying, is not disadvantaged by overhead obstructions however, it is restricted to measurements between visible points in the surveying area. Control points generally located far away from the survey area, therefore traversing with a total station to propagate the control is a time consuming task (CRANENBROECK J, 2005).

To taking full advantage of GNSS system, GNSS receivers must have a clear horizon with the good satellite geometry (WELLENHOF et al., 1992; SUMPTER & ASHER, 1994). On the other hand, if the surveying area cannot be accessible or do not allow surveyors to situate GNSS receiver antenna directly over the points related the surveying area or details, combined measurement techniques can be applied in the practise such as GPS + EDM devices but this kind of combined surveying devices requires very high cost therefore they are not suitable for practise compared to other surveying devices. Usually, companies and institutions have GNSS receiver and total station separately. Since our technique allow us to use these devices separately then we don't need to buy expensive combined GPS+EDM devices. In this point, the need for more affordable and reliable surveying techniques arises for detail surveys. GPSSIT is a surveying technique which based on the centralization of total station's optical center and GNSS receiver's phase center through the same tribrach. To maintaining this concept, firstly one tripod must set up on the ground, then GNSS receiver is situated on this tripod with levelled tribrach. After that, receiver process the GPS observations for determining its position (tribrach surface) which is called Virtual Station, after finishing the observation, receiver separated from its tribrach so it can be replaced with total station using the same tribrach. Lastly, receiver is being set up on the other tripod over the levelled tribach and determines this tribrach surface location for total station orientation. Therefore tribach surface on the first tripod determined as a reference point(Virtual Station) with known coordinate for total station by the GNSS receiver. Finally total station can start surveying for details without using any ground-based points (CORUMLUOGLU & KALAYCI, 2007). GPSSIT concept depends on setting up at least two tripods, two levelled tribrachs and mounting devices (total station and receiver) on the ground. One tripod and its levelled tribrach is needed for centralization between receiver and total station and other tripod and its levelled tribrach is needed for total station orientation. In this point, there are two tripod must set up on the ground but there is no need to any established control point on the ground with known coordinates for the two tripods to creating traverse station (In terms of using CORSE system). For one part of detail surveys, each two tripods with its tribrach must be set up and levelled. After the one part of detail survey, the same process steps have to apply for second part of detail surveys. Taking into consideration of this fact, dependent on each tripod setup, mounting the total station and carrying these survey instruments together on the ground for each part of detail surveys makes the surveying process longer and

harder and adds some additional labour effort when it is compared with surveying process which receiver antenna can be applicable directly and vertically over the details (LEICK, 1990).

In this research, here in housing area of campus, to overcome these difficulties, especially to reducing time requirement for surveying, Motorized GPSSIT technique which is more practical and swift than the GPSSIT technique alone was developed. Thanks to the mobile pick-up vehicle, mobility of surveying increased and time requirement of surveying reduced dramatically compared to the GPSSIT technique alone. In GPSSIT technique, there is always need to setting up at least two levelled tribrach with tripod or generally much more without necessarily established ground-based points with known coordinates for detail surveys which cannot be surveyed directly by GNSS receiver. Motorized GPSSIT technique eliminates this dependency on the ground. After the design stage was completed, system was tested on campus area of to understanding whether it can be reliably accurate, usable and applicable in the practise.

## **2. GPSSIT (GPS VIRTUAL STATION TECHNIQUE)**

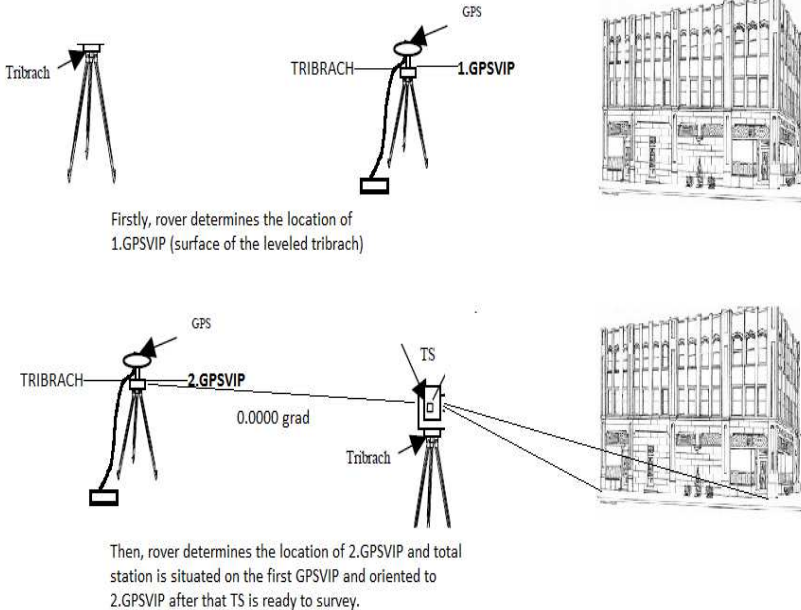
Nowadays, we all realize that classical surveying techniques leave their places very rapidly to modern GPS and Global Navigation Satellite System(GNSS). Naturally, as other surveying techniques GNSS has own special problems in some circumstances. GNSS receivers require an unobstructed view of the sky, so they are used only outdoors and they often do not perform well within forested areas or near tall buildings(YAHYA & KAMARUDIN, 2008).

In open lands, generally, relative positioning technique is chosen. Instead of determining the position of one point on the earth with respect to the satellites (as done in single point positioning) the position of one point on the earth is determined with respect to "another" known point (SCHWARZ & SCHUBERNIGG, 1992; WYLDE & FEATHERSTONE, 1995). Generally, to providing relative positioning technique, Continuously Operating Reference Stations (CORSE) which is dependent on network based RTK have been widely used for surveyors. Network RTK is a centimetre-accuracy, real time, carrier phase-based positioning technique capable of operating over inter-receiver distances up to many tens of kilometres (the distance between a rover and the closest reference station receiver) with equivalent performance to current single base RTK systems (operating over much shorter baselines) (RIZOS, 2002). CORSE has many advantages compared the other GPS surveying techniques. For example, one receiver(rover) is enough to perform surveying without using stationary receiver so it helps surveying procedure to be more swift and easy.

GPSSIT surveying technique depends on necessarily centralization of GPS receiver and Total Station. Using same tribrach, combination of these devices provides that total station's optical centre coordinates can theoretically be determined by a GNSS antenna. Single levelled tribrach via circular vial vertically aligns the phase centre of GNSS antenna and the optical centre of total station along

the plumb line passing through these two special points and this alignment called "single tribrach combination" technique (CORUMLUOGLU & KALAYCI, 2007).

Figure 1 – GPSSIT concept.



In this technique, two GPS or GNSS antenna (one stationary receiver mounted on a ground as a base station with known coordinates for relative positioning and one rover) and only one ground-based control point for base control is needed on which GNSS antenna is situated for sending correction to other receiver (rover) which is on the tribrach. In terms of Using Continuously Operating Reference Station while performing GPSSIN technique, only one GPS receiver which is a rover enough to collect observation data which mean there is no need or desire the second receiver as a stationary receiver mounted as a base station on the ground with known coordinates. The most important advantage of this technique is that like in the aerial triangulation, reference points for detail surveys are created in the air (surface of tribrach) rather than on the ground. Therefore, GPSSIT doesn't depend on any established points on the ground before the survey in terms of using CORSE system.

In this study, reference points (surface of tribrach) for detail surveys determined by GPSSIT technique with two GPS receivers and one total station and

it is called GPSVIP (GPS Virtual Station Point) that it works as a virtual point like in the case of determination of the camera perspective center by GPS system in a GPS supported aerial triangulation process in photogrammetry (CORUMLUOGLU, 1998)

Figure 2 – Levelled tribrach and loosen total station.



Figure 3 –Putting GPS antenna on levelled tribrach.



Detail surveying by GPSSIT with total station is started with the choosing of an appropriate area which maintains total station measurement process for detail surveys and also the collection of GPS signals with a good view of GPS satellites. After choosing the area, rover determines the position of first GPS Virtual Station

Point(GPSVIP) of the levelled tribrach surface which is on the first tripod, after the determination of this point, rover is separated from its tribrach and situated to second levelled tribrach which is on the second tripod (second GPSVIP) and started to determine the position of second GPSVIP. Then, total station is situated on the first tribrach (first GPSVIP) which is levelled before on the first tripod, then total station is levelled more precisely via plate vial, also 3 dimensional coordinates of total station is already determined, after that total station is oriented to the second GPSVIP in order to solve geodetic azimuth between these two points. Now total station is ready to surveying for details.

Detailed descriptions on GPSSIT technique itself, Single Tribrach combination technique and surveying procedures can be found in author's preview paper (CORUMLUOGLU & KALAYCI, 2007).

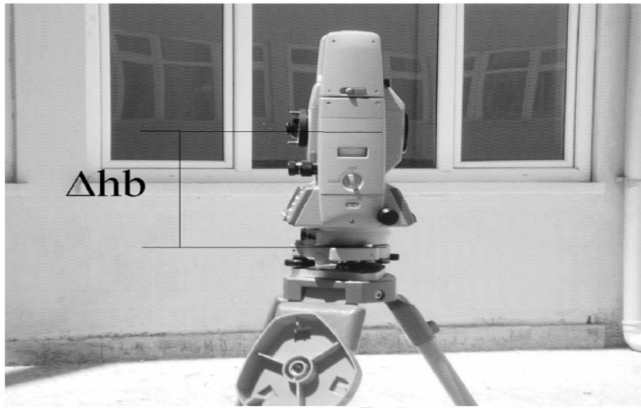
### 3.HEIGHT DETERMINATION BY GPSSIT

GPSSIT surveying technique is also capable of providing heights of points related the details. Therefore, in terms of height determination, GPSSIT technique is available. During the surveying process of this technique, both devices (total station and GPS receiver) uses the same levelled tribrach and should it is levelled once, surface of the tribrach remains stable during the both measurement stages of GPS receiver and total station. Therefore, reference surface of tribrach can be determined for height transformation between both devices. Using GPS antenna offset ( $\Delta h_a$ ) to determine tribrach surface height can be solved by the equation 1. Height of optical center of total station can then be determined using optical center offset of total station ( $\Delta h_b$ ) from the tribrach surface by the equation 2 (BANNISTER et al., 1992; KALAYCI, 2003). GPS antenna offset ( $\Delta h_a$ ) and optical center offset of total station ( $\Delta h_b$ ) from the tribrach surface is determined by steel tape measure with millimeter precision.

Figure 4 – Offset between GPS antenna reference point and reference surface of tribrach.



Figure 5 – Offset between optical center of total station and reference surface of tribrach.



Height transformation can be performed by these two equations:

$$H_T = H_{GPS} - (\Delta h_{offset} + \Delta h_a) \quad (1)$$

$$H_{TS} = H_T + \Delta h_b \quad (2)$$

where,  $H_T$  is the height of the reference surface of tribrach,  $H_{GPS}$  the height of GPS antenna phase center,  $\Delta h_{offset}$  the constant offset value of GPS antenna (0,139 m),  $H_{TS}$  the height of optical center of total station,  $\Delta h_a$  the offset between GPS antenna reference point and reference surface of tribrach,  $\Delta h_b$  the offset between optical center of total station and reference surface of tribrach.

#### 4.MOTORIZED GPSSIT

This technique is the motorized (mobile) version of GPSSIT. In this technique, neither GPS antenna nor Total Station is setup on a tripod which is on the ground but setup on a vehicle with using appropriate apparatus to fix both of devices (receiver and total station) on a pick-up vehicle. As it is known that each tripod setup and mounting the Total Station requires time and labour effort for surveying. Most important advantage of Motorized GPSSIT is that rather than struggling to setting up tripod and mounting Total Station on the ground for creating traverse station and carrying these system for other part of detail surveys, stationary apparatus on the vehicle is using fix to total station and rover. Therefore, surveyors do not need spending time to struggling setting up and carrying instruments for each detail surveys. This independency reduces labour effort and surveying time dramatically. Surveying procedure and measurement theory are the same as those



for ground based GPSSIT.

First of all, GPS antenna is plugged on a tribrach with a specially designed adjustable bar that makes GPS antenna and its tribrach to be fixed on a vehicle body and GPS data can then be collected. Thus, the point called as GPS virtual point (GPSVIP) in GPSSIT is determined in 3D coordinates in this manner. Afterward, GPS antenna is removed from the tribrach and total station is attached to it. Meanwhile, GPS antenna is attached on a surveyor pole located at a place on the vehicle which is possibly far away from the tribrach on the bar. Therefore, most suitable place for the surveyor pole on the vehicle can be the most distant corner of the vehicle body, i.e. pickup. The baseline between these two points on the vehicle determined by the rover as in the GPSSI to creating reference direction for orientation of Total Station while vehicle is stopped for detail surveys. The created baseline distance on the vehicle is short. Therefore, it would inevitably cause slight orientation error for total station. Our empirical comparison shows that this error affect results in negligible level. Once GPS data collection is completed, detail surveying can be started by a surveyor without alighting from the vehicle if a laser total station is used. Once all details measurable by laser total station from the location where the vehicle is stopped, it means that first measurement section can be completed for details while vehicle is stopped on the first station then vehicle can move to another station for other measurement section and so on, until all the details are surveyed in the project area. Therefore, difficulties and time spending associated with setting up and carrying these survey instruments on the ground for each part of detail surveys can be eliminated thanks to Motorized GPSSIT technique.

As mentioned above, the apparatus should be positioned as a telescopic steel profile to fix any vehicle body and a flat surface with screw in the middle should also put to mount GPS antenna and total station on this profile (figure 6).

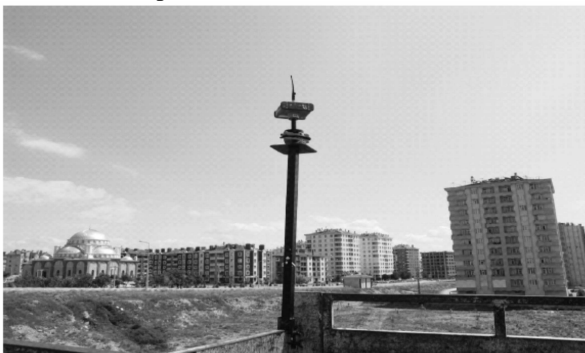
Figure 6 – The apparatus with attached total station used for detail survey.



As mentioned previously, another apparatus should also be designed and put far away from the tribrach, corner of pick-up truck body in order to provide a reference direction for total station orientation as seen in figure 7. During the GPS measurements, Stop & Go, RTK or Network Based RTK GPS surveying techniques can be used as observation technique.

Before starting the detail survey with the total station, some precaution was taken for maintaining stability of the vehicle. For example, the hand brake was on while the surveying process and the operator tries to stand stable while performing survey. After the precaution was taken, very small amount of vibration would occur but generally they affect the results in the order of millimeter. Therefore, the error caused by the vibration is always less than a centimeter. Our equipment's (GPS receiver) accuracy for RTK is 15 millimeter  $\pm$  2 ppm so vibration error is always inside this accuracy.

Figure 7 – Apparatus used to provide reference direction for total station orientation.



General view of both apparatus on the vehicle can be seen from the figure 8 below

Figure 8 –General view of both apparatus on the vehicle.



## 5. CASE STUDIES

First application of the Motorized GPSSIT detail surveys concept was performed to collect data for housing area where the 12 flats (apartments) situated for the university employees. Stop & Go and RTK GPS observation techniques were chosen during the GPS observation sections. As techniques of detail surveys, classical polar detail surveying method, ground based and Motorized GPSSIT methods were applied with Stop & Go and RTK section, Motorized GPSSIT and Classical surveying methods were used in this area and classical one was also chosen reference surveying technique for the comparison. Therefore, horizontal and vertical accuracy related the surveyed points were computed from this comparison by using root-mean-square error (RMSE) to estimate positional accuracy (Table 1, 2,3,4,5,6).

Generally surveyed points are close from the vehicle (maximum range is 100 meters) so our device compensator is more than accurate enough for the range that we are reading the data, (SUMPTER & ASHER, 1994).

$$d_{xi} = X_{GPSSIT} - X_{Ci} \quad (3)$$

$$d_{yi} = Y_{GPSSIT} - Y_{Ci} \quad (4)$$

$$d_{zi} = H_{GPSSIT} - H_{Ci} \quad (5)$$

$$m_x = \pm \sqrt{d_{xi} * d_{xi} / n} \quad (6)$$

$$m_y = \pm \sqrt{d_{yi} * d_{yi} / n} \quad (7)$$

$$m_h = \pm \sqrt{d_{hi} * d_{hi} / n} \quad (8)$$

$$m_p = \pm \sqrt{(d_{xi} * d_{xi} + d_{yi} * d_{yi}) / n} \quad (9)$$

Where  $d_{xi}$ ,  $d_{yi}$  are the coordinate differences for the same detail point (i) from both measurement techniques,  $d_{zi}$  the orthometric height differences for the same detail point (i) from both measurement techniques,  $X_{GPSSIT}$ ,  $Y_{GPSSIT}$  the coordinates of  $i^{th}$  detail from GPSSIT with total station,  $H_{GPSSIT}$  the orthometric height of  $i^{th}$  detail from GPSSIT with total station,  $X_{Ci}$ ,  $Y_{Ci}$  the coordinates of  $i^{th}$  detail from classical technique,  $m_x$  the standard deviation of virtual error in X coordinate,  $m_y$  the standard deviation of virtual error in Y coordinate,  $m_h$  the standard deviation of virtual error in vertical coordinate,  $m_p$  the standard deviation of positioning error,  $n$  the number of detail points which is measured. Coordinates were determined in ITRF datum then they were transformed to ED50 datum for GPSSIT and Motorized

GPSSIT technique. ED50 datum was used with Classic technique without any transformation. All comparisons are done in ED50 datum.

Field data have been checked for acceptable distribution by statistical tests. Normal distribution has been observed. Since the distribution graphics take so much space so they have not been included in this paper.

The level of the errors is checked as follows; after all the readings are done, we choose an arbitrary reading and we go ahead read this point again to make sure that previous reading and new reading are in acceptable agreement.

Table 1 – Comparison of the techniques in Stop & Go GPS surveying mode for the points which can be surveyed directly by GPS.

Methods	Num. of Details (n)	$m_p$ (cm)	$m_h$ (cm)
Classic-GPSSIT	188	4,92	4,03
Classic- Motorized GPSSIT	188	5,07	4,19
GPSSIT-Motorized GPSSIT	277	4,61	3,95

Table 2 – Comparison of the techniques in Stop & Go GPS surveying mode for points which cannot be surveyed directly by GPS.

Methods	Num. of Details	$m_p$ (cm)
Classic-GPSSIT	112	5,19
Classic- Motorized GPSSIT	112	5,28
GPSSIT-Motorized GPSSIT	198	4,77

Table 3: Comparison of the techniques in RTK GPS surveying mode for points which can be surveyed directly by GPS

Methods	Num. of Detai	$m_p$ (cm)	$m_h$ (cm)
Classic- Motorized GPSSIT	180	5,12	4,87

Table 4: Comparison of the techniques in RTK GPS surveying mode for points which cannot be surveyed directly by GPS.

Methods	Num. of Details	$m_p$ (cm)
Classic- Motorized GPSSIT	117	5,41

The second application of the method was carried out in Bosna-Hersek district of Konya. In this application, GPS RTK observation techniques were chosen as GPS observation technique and classical and motorized GPSSIT techniques were used as detail surveying methods. In the case of GPS RTK application, it becomes possible to produce final coordinates of details instantly in surveying process since

RTK or network based RTK is used which mean is there is no need to post processing of GPS observation. Therefore, RTK becomes more convenience for surveyors than other GPS observation techniques. Results from the second application area summarized in table 3.

Table 5: Application carried out in Bosna-Hersek district with RTK GPS surveying mode for points which can be surveyed directly by GPS.

Methods	Num. of Details	$m_p$ (cm)	$m_h$ (cm)
Classic-Motorized GPSSIT	203	4,21	3,68

Table 6: Application carried out in Bosna-Hersek district with RTK GPS surveying mode for points which cannot be surveyed directly by GPS.

Methods	Num. of Details	$m_p$ (cm)
Classic-Motorized GPSSIT	74	4,11

## 6.CONCLUSION

One of the most important benefits of using Motorized GPSSIT is that makes the surveying procedure independent of ground-based traverse station which requires to setting up tripod, mounting the instrument, leveling the instrument and carrying these surveying equipments together for other part of detail surveying in the situation which satellite navigation system doesn't work efficiently. This independency also helps to eliminate some mistakes in traversing such as occupying or sighting on the wrong station or mounting total station over the points which its known position changed due to the construction or any activities around the points. Motorized GPSSIT is enormously beneficial in terms of reducing time requirement of surveying process. Motorized GPSSIT also helps to maintaining GNSS accuracy when GPS or GNSS receivers cannot be performed directly due to the some handicaps of surveying area or signal interference. By considering applicability and economical efficiency in terms of surveying period, cost and labour force, it is seen that Motorized GPSSIT is very productive technique when it is used alone with Stop & Go and/or RTK GPS observation techniques.

For the future studies, it is considered to create a much more comprehensive comparison in terms of time, cost and application with great extent of data.

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